

Basics of Geometry of \mathbb{H}^3 :

①

$$\mathbb{H}^3 = \{ (x, y, u) \in \mathbb{R}^3 : u > 0 \}$$

$\gamma(t)$ a p.wise diff. curve in \mathbb{H}^3 , $\gamma(t) = (x(t), y(t), u(t))$

its hyperbolic length is

$$l_{\text{hyp}}(\gamma) = \int_a^b \frac{\sqrt{x'(t)^2 + y'(t)^2 + u'(t)^2}}{u(t)} dt$$

$$\text{metric is } (ds)^2 = \frac{dx^2 + dy^2 + du^2}{u^2}$$

\mathbb{H}^3 admits several "obvious" isometries:

horizontal translations: $\varphi(x, y, u) = (x + x_0, y + y_0, u)$
 $x_0, y_0 \in \mathbb{R}$

homotheties / scaling: $\varphi(x, y, u) = (\lambda x, \lambda y, \lambda u)$
for $\lambda \in \mathbb{R}$

and rotations around u -axis defined by

$$\varphi(x, y, u) = (\underbrace{x \cos \theta - y \sin \theta}_{x'}, \underbrace{x \sin \theta + y \cos \theta}_{y'}, u)$$

for $\theta \in \mathbb{R}$

Coming from rotation of \mathbb{C} within \mathbb{H}^3 : $e^{i\theta} z =$
 $(\cos \theta + i \sin \theta)(x + iy) \rightsquigarrow x \cos \theta - y \sin \theta + i(x \sin \theta + y \cos \theta)$
 $\text{Re}(\hat{}) = x' \quad \text{Im}(\hat{}) = y'$

Analog of inversion across unit circle is inversion across unit sphere $\varphi: \mathbb{R}^3 \cup \{\infty\} \rightarrow \mathbb{R}^3 \cup \{\infty\}$

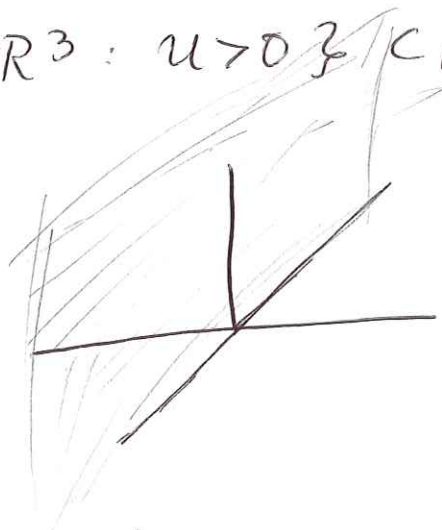
$$\varphi(x, y, u) = \left(\frac{x}{x^2 + y^2 + u^2}, \frac{y}{x^2 + y^2 + u^2}, \frac{u}{x^2 + y^2 + u^2} \right)$$

Setting $y=0$ $H = \{(x, 0, u) \in \mathbb{R}^3 : u > 0\} \subset \mathbb{H}^3$

has natural ident. w/ \mathbb{H}^2 .

Think of $\mathbb{C} \subset \mathbb{H}^3$ as $\{(x, y, 0)\}$
 (xy-plane)

Isometries:



Every linear or antilinear fractional trans. of $\hat{\mathbb{C}}$ continuously extends to a map $\hat{\varphi}: \mathbb{H}^3 \cup \hat{\mathbb{C}} \rightarrow \mathbb{H}^3 \cup \hat{\mathbb{C}}$ whose restriction to \mathbb{H}^3 is an isometry.

Pf: any such map is a composition of trans, rotations, scaling and inversions across unit circle which all extend to isoms of \mathbb{H}^3 as we stated above.

Conversely, every isom. of \mathbb{H}^3 is obtained as an extension of a linear or antilinear frac. trans.

Pf: P. 232 - 233 Bonahon

Note: A good way to think about this is that the inversions about circle extend to inversions about orthogonal hemisphere whose boundary is that circle in $\hat{\mathbb{C}}$.

Classification of Orientation Preserving Isoms of \mathbb{H}^3 : ③

Now that we know every orientation preserving isom. of \mathbb{H}^3 arises as an extension of a linear fractional trans.

of $\hat{\mathbb{C}}$. $\varphi(z) = \frac{az+b}{cz+d}$ $a, b, c, d \in \mathbb{C}$, $ad-bc \neq 0$.
 i.e. $ad-bc = 1$.

$\varphi(z)$ fixes exactly one or two points of $\hat{\mathbb{C}}$.

$$z = \frac{az+b}{cz+d} \Rightarrow cz^2 + (d-a)z - b = 0$$

$$z = \frac{a-d \pm \sqrt{(d-a)^2 + 4bc}}{2c} \quad \left. \begin{array}{l} 1 \text{ if } (d-a)^2 + 4bc = 0 \\ 2 \text{ if } \neq 0. \end{array} \right\}$$

1) If φ fixes one point $z_0 \in \hat{\mathbb{C}}$, let ψ be hyp isom sending $z_0 \mapsto \infty$. ~~Then~~ Then $\psi \circ \varphi \circ \psi^{-1}$ is a horiz. trans. Pf: $\varphi(\infty) = \frac{a}{c} = \infty \Rightarrow c=0$.

$c=0$ and φ has one fixed point so $\sqrt{(d-a)^2 + 4bc} = \sqrt{(d-a)^2} = d-a = 0 \Rightarrow a=d$. Thus,

$$\frac{az+b}{cz+d} = \frac{az+b}{0+a} = z + b/a. \quad b, a \in \mathbb{C}$$

φ is said to be parabolic (conjugate to ^{horiz.} translation in \mathbb{H}^3)

2) If φ fixes two points $z_1, z_2 \in \hat{\mathbb{C}}$. Let ψ be hyperbolic isom sending $z_1 \mapsto 0, z_2 \mapsto \infty$.

Then $\varphi(0) = \frac{b}{d} = 0 \Rightarrow b=0$ and $\varphi(\infty) = \frac{a}{c} = \infty \Rightarrow c=0$

$$\Rightarrow \varphi(z) = \frac{az+b}{cz+d} = \frac{az}{d} = a/d z \quad (4)$$

So $\psi \circ \varphi \circ \psi^{-1}$ is a homothety-rotation $z \mapsto a_0 z$ with $a_0 \in \mathbb{C} - \{0\}$. φ fixes the complete hyperbolic geodesic btwn. z_1 and z_2 , and acts on the geodesic by translation. If φ fixes every point of g (i.e. $|a_0|=1$ and $a_0 = "e^{i\theta}"$) then φ is called elliptic (pure rotation).

Otherwise φ is called loxodromic (scale + rotate).

Classification of orientation reversing isoms of \mathbb{H}^3 :

$\varphi: \mathbb{H}^3 \rightarrow \mathbb{H}^3$ is isometric extension of an anti-linear fractional map $\varphi(z) = \frac{c\bar{z}+d}{a\bar{z}+b}$ s.t. $ad-bc=1$

$\varphi: \hat{\mathbb{C}} \rightarrow \hat{\mathbb{C}}$ and consider $\varphi^2 = \varphi \circ \varphi$.

$\varphi^2(z) = \frac{(d\bar{a} + \|c\|^2)z + c\bar{d} + d\bar{b}}{(a\bar{c} + b\bar{a})z + a\bar{d} + \|b\|^2}$ is a linear fractional trans.

$$(a'd' - b'c' = +1)$$

φ sends each fixed point of φ^2 to a fixed point of φ^2 . If φ^2 has two fixed points and z_1 is one of them then $\varphi^2(z_1) = z_1 \Rightarrow$ if $\varphi(z_1) = z_2$ then $\varphi(\varphi(z_1)) = \varphi(z_2) = z_1$, but then z_2 is also a fixed pt. of φ^2 . $\varphi(\varphi(z_2)) = \varphi(z_1) = z_2$

If φ^2 has 1 f.p. and it is z_1 then $\varphi(\varphi(z_1)) = z_1 \Rightarrow \varphi(z_1) = z_1$ (5)
 otherwise $\varphi(z_1) = z_2$ and z_2 is also a f.p. of φ^2 .

1.) Suppose φ^2 is parabolic and $\varphi^2 \neq \text{id}$. \exists hyp isom.

ψ s.t. $\psi \circ \varphi \circ \psi^{-1}$ is the composition of the Euclidean reflection across a vertical Euclid. plane w/ a horizontal translation along a vector (nonzero) ~~the~~ parallel to that plane.

Pf: φ^2 is parab. $\Rightarrow \exists \psi$ s.t. $\psi \circ \varphi^2 \circ \psi^{-1} = z + b$
 where $b \in \mathbb{C}$ as we proved earlier in our classification of orientation preserving isoms of \mathbb{H}^3 .

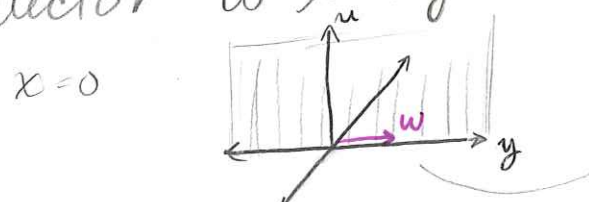
$$\Rightarrow (\psi \circ \varphi \circ \psi^{-1}) (\psi \circ \varphi \circ \psi^{-1}) = z + b \Rightarrow \psi \circ \varphi \circ \psi^{-1} = -\bar{z} + w$$

where $w - \bar{w} = b$ \otimes $(b \in \mathbb{C} - (-\bar{z} + w) + w = z - \bar{w} + w)$

$\Rightarrow b = y_0 i$ for some y_0 . Note that diff. choices of ψ give diff. w satisfying \otimes .

but w must always be of the form $x_0 + \frac{1}{2} y_0 i$ so by composing w/ a translation by $-x_0$ we can ensure that \exists an isometry ψ' s.t. $\psi' \circ \varphi \circ (\psi')^{-1}$ is of the form $-\bar{z} + \frac{1}{2} y_0 i$ so w is purely imag. The $-\bar{z}$ is

a flip across the y axis of $\mathbb{C} \subset \mathbb{H}^3$ so its extension is a flip across the plane $x=0$ in \mathbb{H}^3 and the vector w being imaginary is parallel to the plane



\rightarrow note $w = \frac{1}{2} y_0 i$ purely imag. \Rightarrow parallel

2.) Suppose φ^2 fixes two points $z_1, z_2 \in \hat{\mathbb{C}}$ and $\varphi^2 \neq \text{id}$. (6)

Case 1: Suppose φ also fixes each of z_1, z_2 ($\varphi(z_1) = z_1$, $\varphi(z_2) = z_2$). Then $\exists \psi$ s.t. $\psi \circ \varphi \circ \psi^{-1}$ is the composition of a homothety w/ a reflection across a vertical euclidean plane passing through the point 0. $\psi \circ \varphi \circ \psi^{-1}$ fixes 0 and ∞ and is of the form $\frac{c\bar{z} + d}{a\bar{z} + b}$ w/ $ad - bc = 1$. 0 fixed $\Rightarrow d = 0$ and ∞ fixed $\Rightarrow a = 0 \Rightarrow ad - bc = -bc = 1$ and $c = -\frac{1}{b}$ so $\psi \circ \varphi \circ \psi^{-1} = -\frac{1}{b^2} \bar{z} = \frac{1}{b^2} \cdot -\bar{z}$. The $-\bar{z}$ reflects across the y -axis of $\mathbb{C} \subset \mathbb{H}^3$ and so $-\bar{z}$ extends to a reflection about the vertical plane $x = 0$. The $\frac{1}{b^2}$ is a homothety and one should note that for any such ψ , $\psi \circ \varphi \circ \psi^{-1} = -\lambda \bar{z}$ where $\|\lambda\| \neq 1$ otherwise, $(\psi \circ \varphi \circ \psi^{-1}) \circ (\psi \circ \varphi \circ \psi^{-1}) = \psi \circ \varphi^2 \circ \psi^{-1} = \lambda \bar{\lambda} z = \|\lambda\|^2 z = z$ but φ^2 fixes exactly two points so $\psi \circ \varphi^2 \circ \psi^{-1} \neq \text{id}$. Thus, $\psi \circ \varphi \circ \psi^{-1} = -\lambda \bar{z}$ where λ contributes a homothety-rotation.

φ respects the complete geodesic g from z_1 to z_2 and acts on g by translation.

φ is called orientation reversing loxodromic

3.) Suppose φ^2 fixes ^(only) z_1 and z_2 and φ exchanges z_1 and z_2 (these are the two cases that can happen since φ fixes the f.p. set of φ^2) Let ψ be w.o.m. sending $z_1 \mapsto 0$ and $z_2 \mapsto \infty$. Then $\psi \circ \varphi^2 \circ \psi^{-1}$ is a scaling/homothety. And $\psi \circ \varphi \circ \psi^{-1}$ exchanges 0 and $\infty \Rightarrow \frac{c\bar{z} + d}{a\bar{z} + b}$ becomes $\frac{d}{a\bar{z}}$ since 0 fixed

$$\Rightarrow \frac{d}{b} = \infty \Rightarrow b = 0 \text{ and } \infty \mapsto 0 \Rightarrow \frac{c}{a} = 0 \Rightarrow c = 0$$

Also though, \mathcal{Q} is an anti linear fact. trans. $\Rightarrow ad-bc=1$ $\textcircled{7}$
 $\Rightarrow ad=1$ in our case and $a = \frac{1}{d}$. Thus,

$$\psi \circ \mathcal{Q} \circ \psi^{-1} = \frac{dz}{\bar{z}} = dz \cdot \frac{z}{\|z\|^2}. \text{ Let } \psi'(z) = \frac{1}{d} z \text{ a hyp.}$$

isometry. Then, $\psi' \circ \psi \circ \mathcal{Q} \circ \psi^{-1} \circ (\psi')^{-1}(z) = \mathcal{Q}$

$$\psi'(\psi \circ \mathcal{Q} \circ \psi^{-1})(dz) = \psi'\left(\frac{dz}{\bar{z}}\right) = \frac{1}{d} \cdot \frac{dz}{\bar{z}} = \frac{dz}{\|d\|^2} \cdot \frac{1}{\bar{z}} = \lambda \frac{1}{\bar{z}}$$

The $\frac{1}{\bar{z}} = \frac{z}{\|z\|^2}$ contributes an inversion about a circle

centered at zero which extends to an inversion about a hemisphere $\subset \mathbb{H}^3$ centered at O . Also, $\|\lambda\| = \left\| \frac{dz}{\|d\|^2} \right\| = 1$

so $\lambda = \frac{d^2}{\|d\|^2}$ contributes a ^{pure} rotation about the u -axis.

so $\exists \tilde{\psi}$ a hyp. isometry s.t. $\tilde{\psi} \circ \mathcal{Q} \circ \tilde{\psi}^{-1}$ is the composition of an inversion about a hemisphere and a rotation about the u -axis by an angle θ that is not an integer mult. of π . (The restriction on θ comes

from the fact that $\tilde{\psi} \circ \mathcal{Q}^2 \circ \tilde{\psi}^{-1} = (\tilde{\psi} \circ \mathcal{Q} \circ \tilde{\psi}^{-1}) \circ (e^{i\theta}/\bar{z})$

$$= \frac{e^{i\theta}}{e^{-i\theta}} z = e^{i2\theta} z \text{ and if } \theta = k\pi, 2\theta = 2\pi k$$

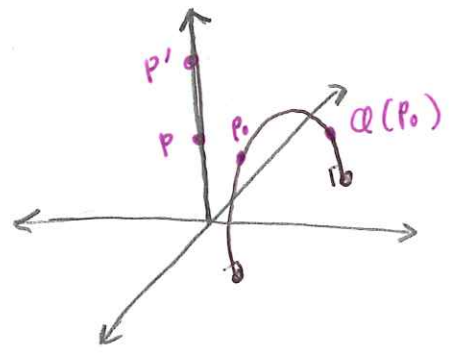
$\Rightarrow \tilde{\psi} \circ \mathcal{Q}^2 \circ \tilde{\psi}^{-1} = \text{id}$ but this can't be since the isom

has exactly 2 fixed points.

(In this case \mathcal{Q} is called orientation reversing elliptic.

(has a f.p. on interior of \mathbb{H}^3 namely $(x_0, y_0, u_0) = (0, 0, 1)$)

4) Suppose $Q^2 = \text{id}$. Choose an arbitrary point $P_0 \in \mathbb{H}^3$ NOT fixed by Q . (such a point exists since $Q \neq \text{id}$). Let g be the unique complete geodesic btwn. $Q(P_0)$ and P_0 , and let Ψ be the hyperbolic isom. taking g to the geodesic btwn 0 and ∞ in \mathbb{H}^3 .



Then $\Psi \circ Q \circ \Psi^{-1}$ is an isom. of \mathbb{H}^3 taking a point $P \in [0, \infty]$ to $P' \in [0, \infty]$ as in the figure above. The possible isoms. that do this are:

$$(0, 0, u) \mapsto (0, 0, \lambda u) \quad \lambda \in \mathbb{C} - \{0\}$$

$$(0, 0, u) \mapsto (0, 0, 1/u) \quad \text{inversion about a sphere}$$

(trans. won't do it cause $(0, 0, u)$ would map to $(x_0, y_0, u) \notin [0, \infty]$)

So $\Psi \circ Q \circ \Psi^{-1}$ must be an antilinear free. trans. as well. Thus, $\Psi \circ Q \circ \Psi^{-1}$ is either an inversion about a

sphere (i.e. $\Psi \circ Q \circ \Psi^{-1} = \frac{1}{z} = \frac{\bar{z}}{\|z\|^2}$) or $\Psi \circ Q \circ \Psi^{-1}$ is
 (many fixed points in \mathbb{H}^3)

the composition of such an inversion with a homothety (i.e. $\Psi \circ Q \circ \Psi^{-1} = \frac{\lambda}{z}$)

~~But for the homothety we can simplify. First note that $\Psi \circ Q^2 \circ \Psi^{-1} = \frac{\lambda}{\lambda} z = z \Rightarrow \lambda/\bar{\lambda} = 1 \Rightarrow \lambda = \bar{\lambda}$~~

and thus $\lambda \in \mathbb{R} - \{0\}$. If $\lambda > 0$ then let $\psi'(z) = \frac{1}{\sqrt{\lambda}} z$. then $\textcircled{?}$

$$\exists \tilde{\psi} \text{ s.t. } \tilde{\psi} \circ \varphi \circ \tilde{\psi}^{-1} = \psi' \circ \varphi \circ \psi'^{-1} = \frac{1}{\sqrt{\lambda}} \cdot \frac{1}{\sqrt{\lambda}} \cdot \frac{\lambda}{z} = \frac{\lambda}{\sqrt{\lambda} \sqrt{\lambda}} \cdot \frac{1}{z}$$

$$= \frac{1}{z} \quad (\text{b/c } \lambda \in \mathbb{R}_{>0} \sqrt{\lambda} = \sqrt{\lambda}) \text{ thus we are in the case of a}$$

pure involution about a sphere. For $\lambda < 0$ let $\psi' = \frac{1}{\sqrt{\lambda}} z$.

$$\text{Then } \exists \tilde{\psi} \text{ s.t. } \tilde{\psi} \circ \varphi \circ \tilde{\psi}^{-1} = \frac{1}{\sqrt{\lambda}} \cdot \frac{1}{\sqrt{\lambda}} \cdot \frac{\lambda}{z} = \frac{\lambda}{-\lambda} \cdot \frac{1}{z}$$

(if $\sqrt{\lambda} = ri$ then $\sqrt{\lambda} \cdot \sqrt{\lambda} = r^2$ and $\lambda = -r^2$).

$$\text{So } \tilde{\psi} \circ \varphi \circ \tilde{\psi}^{-1} = -\frac{1}{z} = \frac{e^{i\pi}}{z} \Rightarrow \text{involution about sphere}$$

composed with a rotation by $\pi = \theta$ about u -axis.

So summarizing the above gives the following list of ALL isometries of \mathbb{H}^3 :

Orientation Preserving: $\varphi(z) = \frac{az+b}{cz+d}$ where $ad-bc=1$ $\left. \begin{array}{l} \text{isom. of} \\ \mathbb{H}^3 \text{ is an} \\ \text{ext. of this} \\ \text{isom on } \hat{\mathbb{C}}. \end{array} \right\}$
 $a, b, c, d \in \mathbb{C}$

1) Parabolic: φ fixes exactly one point in $\hat{\mathbb{C}} \subseteq \mathbb{H}^3$.

φ is conjugate to an isom. of the form $z \mapsto z+a$ where $a \in \mathbb{C} - \{0\}$.
 The extension being an isom. of \mathbb{H}^3 corresponding to a horiz. trans.

2) a) homothety: φ fixes exactly two points in $\hat{\mathbb{C}}$

φ is conjugate to an isom. of the form $z \mapsto \lambda z$ where $\lambda \in \mathbb{R}_{>0}$.
 So the extension is an isometry of \mathbb{H}^3 corr. to a pure scaling
 by a real number.

b) loxodromic: φ fixes exactly two points in $\hat{\mathbb{C}}$

φ is conjugate to an isom. of the form $z \mapsto \lambda z$ where $\lambda \in \mathbb{C} - \{0\}$.
 The extension is an isom. of \mathbb{H}^3 corr. to scaling and rotating about u -axis

c) Elliptic (Pure Rotation) : Φ fixes every point of a geod. g in \mathbb{H}^3 . Φ is conj. to an isom. of the form $z \mapsto \lambda z$ where $\lambda \in \mathbb{C} - \{0\}$ and $|\lambda| = 1 \Rightarrow$ of the form $z \mapsto e^{i\theta} z$. The extension is an isom. of \mathbb{H}^3 that is a pure rotation about the u -axis by an angle θ . (10)

Orientation Reversing Isoms: $\Phi(z) = \frac{c\bar{z} + d}{a\bar{z} + b}$ $a, b, c, d \in \mathbb{C}$
 $ad - bc = 1$.
 isoms are extensions of the isoms on $\hat{\mathbb{C}}$ to all of \mathbb{H}^3 .

1) orientation reversing parabolic: Φ has one fixed point in $\hat{\mathbb{C}}$.

Φ is conjugate to an isom. of the form $z \mapsto -\bar{z} + ri$ and the extension to \mathbb{H}^3 is the composition of a Euclidean reflection across a vertical plane (the uy -axis) with a horiz. translation along a vector (nonzero) parallel to that plane.

2) Orientation reversing loxodromic: Φ has two fixed points in $\hat{\mathbb{C}}$. Φ is conj. to an isom. of the form $z \mapsto -\lambda\bar{z}$ where $|\lambda| \neq 1$ so the extension to \mathbb{H}^3 is the composition of a homothety-rotation with a reflection across a vertical euclidean plane passing thru the point 0 (uy -axis etc.).

3) Orientation Reversing Elliptic: Φ has a fixed point in the interior of \mathbb{H}^3 . Φ is conj. to an isom. of the form

$z \mapsto \frac{\lambda}{\bar{z}}$ where $|\lambda| = 1$, so the extension is an isom. of \mathbb{H}^3 that is a composition of ~~an~~ an inversion about a hemisphere $\subset \mathbb{H}^3$ centered at 0 and a pure rotation about the u -axis by an angle θ that is not an integer mult. of π .

4) Φ is an isom. of \mathbb{H}^3 that is a pure inversion about a sphere ($z \mapsto \frac{1}{\bar{z}}$) or $z \mapsto \frac{-1}{\bar{z}} = \frac{e^{i\pi}}{\bar{z}}$ an inversion about sphere plus rotation by π .
 Fixed pts. on hemisp. if fixed pt. \subset in \mathbb{H}^3 .

Now that we know all of the isoms. of H^3 we can show which of these can be elements of deck trans. groups for hyperbolic 3-mfds.

The only options are $OP2a$, $OP2b$, and $OR2$. The parabolic isoms. are ruled out due to the same reasoning as in the 2D case.

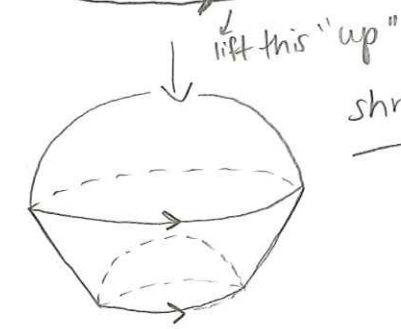
Next we will study what the \mathbb{Z} -covers of a hyperbolic 3-mfd. could be.

Case 1: ($OP2a$) Orientation preserving homothety.

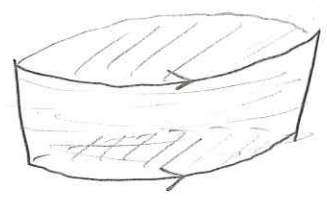
Suppose $\varphi(z)$ is the extension of the isom. $z \mapsto Rz$ where $R \in \mathbb{R}_{>0}$. A fund. region for the action of φ on H^3 is the region between the hemisphere of radius 1 and the hemisphere of radius R .



the regions in \hat{C} are not included / open. identifying points in H_1 to their images in H_R :



shrink/collapse hemispheres



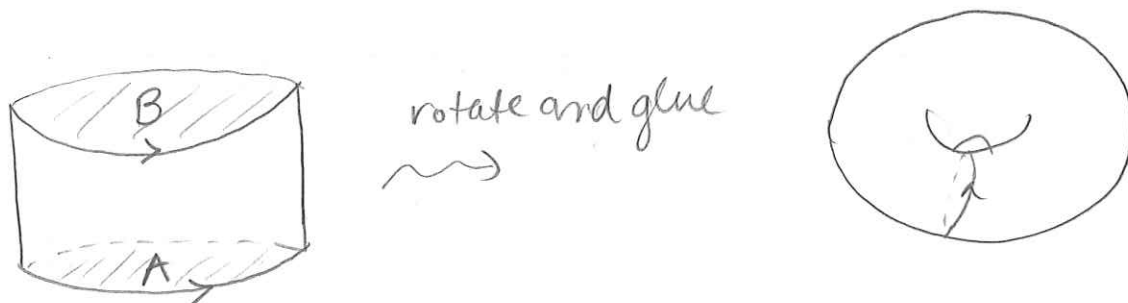
(solid)
↙

Identify two discs which were the two hemispheres



open, solid torus

Case 2 (OP2b): This is orientation preserving lexodromic⁽¹²⁾ case, where the only difference from case 1 is the additional rotation by θ . However, this rotation can simply be interpreted as a rotation of face (aka disc) A by θ before gluing to face/disc B:



Topologically we still have an open, solid torus (just with a twist).

Case 3: (OR2) orientation reversing lexodromic (or homothety) The difference from case 1 and 2 lies in the fact that H_L corresponding to disc/face A is glued to H_R (corr. to disc/face B) ~~and~~ after a reflection across the xy -axis (or some other vertical plane thru O).

Instead of: we have:



this identification results in